



## AllMotion MSRS 360 Controller Example:

1. Unzip the AllMotion360ControllerExample.zip folder.
2. Copy and paste the folder that you unzipped to your Microsoft Robotics Studio folder.
3. Open the project in MSRS.

This example requires an XBOX 360 controller and 2 EZHR17EN's. The XBOX controller is set up to send velocity and direction commands to the EZSteppers. You can easily delete the second controller to run a single motor.